

平成 28 年 2 月 26 日

国立研究開発法人
産業技術総合研究所 殿

検査成績書

売買契約書 整理番号 AA15046738

表題：自動太陽追尾サンフォトメーター 1 式

	動作確認
電気ボックス	合格
アンテナ	GSM, RADIO、GPS 合格
センサヘッド	CE318T TU9 (BRDF) 合格
コリメーター	合格
太陽自動追尾用ロボット	動作確認 合格
AC/DC アダプタ (100VAC を 12VDC 変換)	合格
CD-ROM (計測ソフトウェア)	合格
USB ケーブル、その他ケーブル類	合格
光学フィルター9種類 of データ (電子、印刷)	合格
光学ワイプ (光学窓クリーニング用)	合格
取り扱い説明書 (ハードウェア) 1 冊 (英文)	合格
同、計測ソフトウェア用	合格

以上動作確認の上納品させて頂きました。

〒231-0004 横浜市新元浜町 8-121-2
ヘリオス館内ビル 301 号室
ホロニクス・インターテック株式会社
代表取締役 高橋 邦明

Automatic PHOTOMETER **CE 318 - TU9**

Date	February , 2016
Customer	Japan
Order N°	150207

STATEMENT of TESTS & CONFORMITY

	Qt.	Part	N °
X	1	Electronic box CE 318 - C	1602 - 038 / UA 4797
X	3	Antenna for electronic box " 97685 " " 97686 " " 97687 "	GSM Radio GPS
X	1	Head CE 318 - T	1602 - 039 / T 1320 TU9
X	1	Collimator	CL 211 - 1379xx - 1517
X	1	Head photometer's cable	15 pts 12 m
X	1	Azimuthally Robot CE 318 - M	1602 - 040 with calib report
X	1	Robot motor's calibration report	AZ & ZN 12m cable
X	1	Cable collar	PVC Nicoll
X	1	Directional Antenna	5m cable
	with	Solar panel	K S 5 - 12V <i>Phoenix</i>
	with	Wetness sensor	CE 187 1,5 m
X	1	Lighting rod with M10 nut	
X	1	Copper braided wire for ground network 16mm ² in 25m coils with one copper tubular lug M10	
X	1	Earth rod + lug	
X	1	Couple of batteries 6V	with cable
X	1	Supply 100 ~ 240 V <i>MASCOT</i>	SP green connector / plug cable
X	1	PC serial transfer cable	PC / DCP
X	1	PC transfer cable USB A - USB B	USB " 89024 "
X	9	Paper printed filter curves	T 1320 TU9
X	1	CD ROM with filters data files	
X	1	Cleaning optic cloth	

CIMEL Electronique

172 rue de CHARONNE - 75 011 - PARIS

Tel : 33 - 1 43 48 79 33

Web: <http://www.cimel.fr>

HEAD NUMBER **1320** TU9

DATE Feb 2016

SKY & GROUND CALIBRATION

wavelength	1020	1640	870	675	440	550	740
Coef AUREOL	2.4080E-05	4.4650E-06	2.3638E-05	2.8831E-05	5.1214E-05	3.7636E-05	3.5054E-03
	1020	1640	870	675	440	550	740
Coef SKY	7.5015E-07	1.3910E-07	7.3638E-07	8.9726E-07	1.5943E-06	1.1713E-06	1.0896E-04
		1640	870	675	440	550	740
Coef GROUND	7.5015E-07	1.3910E-07	7.3638E-07	8.9726E-07	1.5943E-06	1.1713E-06	1.0896E-04

Coef = Radiance/Digital Count

Radiance W/m².sr.nm

Wavelength : nm

SUN CALIBRATION

	1020	1640	870	675	440
CNO	633272	1035851	835911	1097562	754683
	550	1020i	936	380	740
CNO	990214	824539	618946	138192	947948

Equipement

ASTP Optique

CE 318 BRDF 9F

In Ga As
Judson

Tête N° >	T 1320 BRDF	
UA N° >	UA 4797	
		Japon

	désignation	cde	code P.	Code lot	batch	N° #
A4	filtre 440 BP 10 nm IRIDIAN (Canada)	810362	74052 IR	ABX000005	006	19043
A3	filtre 675 BP 10 nm JDSU (USA)	810364	74062 JD		03	413
A2	filtre 870 BP 10 nm IRIDIAN (Canada)	810365	74068 IR	ABX000008	005	13938
WV2	filtre 937 BP 10 nm IRIDIAN (Canada)	810366	74070 IR	ABX000009	004	19293
A1	filtre 1020 BP 10 nm IRIDIAN (Canada)	810367	74072 IR	ABX000010	007	18300
UV2	filtre 740 BP 2 nm BK	810360	74049 IR	ABX000003	n°3	#
UV1	filtre 380 BP 4 nm IRIDIAN (Canada)	810361	74050 IR	ABX000004	007	17362
N	filtre 550 BP 10 nm BK	810363	74054 JD		02/03	11
WV1	filtre 1640 BP 25 nm IRIDIAN (Canada)	810368	74077 IR	ABX000012	006	16919

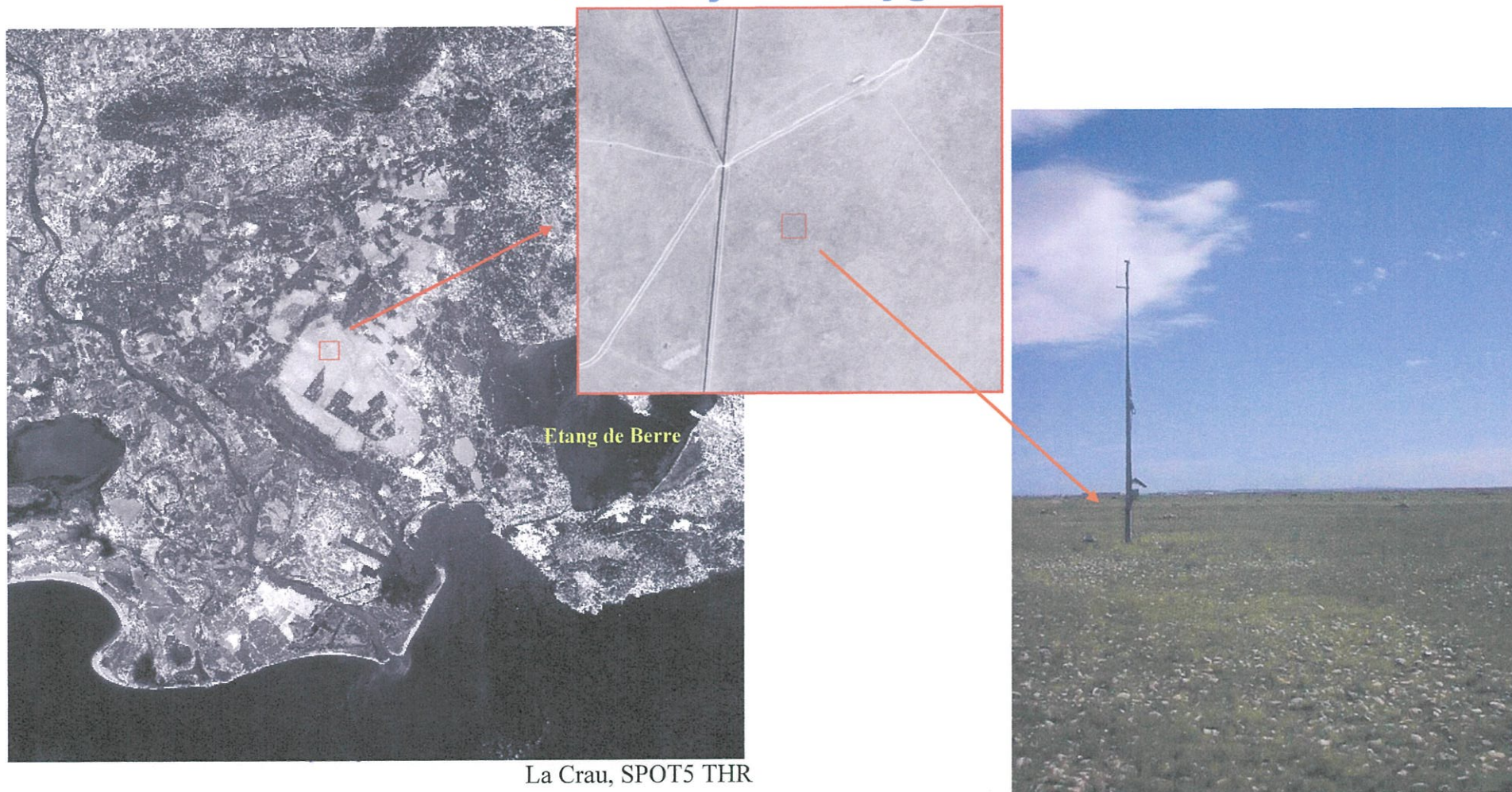


La Crau - ROSAS



(RObotic Station for Atmosphere and Surface)

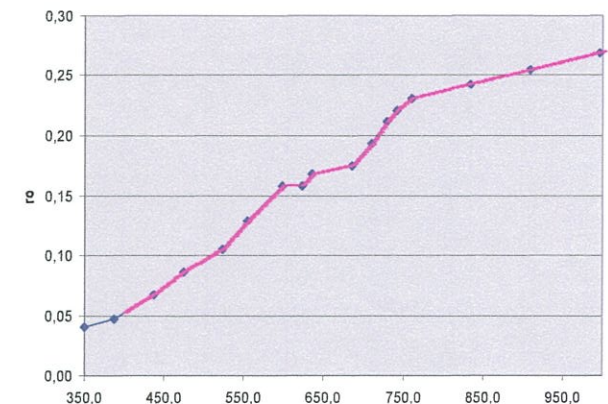
P. Henry - A. Meygret



La Crau, SPOT5 THR



- ❑ Situation: La Crau
 - ❑ located South-East of France (lat. = 43.56° ; long. = 4.86°)
 - ❑ rather good surface stability (dry area with small rocks)
- ❑ Calibration historic
 - ❑ first CNES campaign in march 1989 (coop. with LOA and INRA)
 - ❑ 9 SPOT 1 calibrations (1989 \Rightarrow 1993)
 - ❑ In 1994 : decision to develop an automatic calibration station



- CIMEL Instrument
(derived from AERONET one)



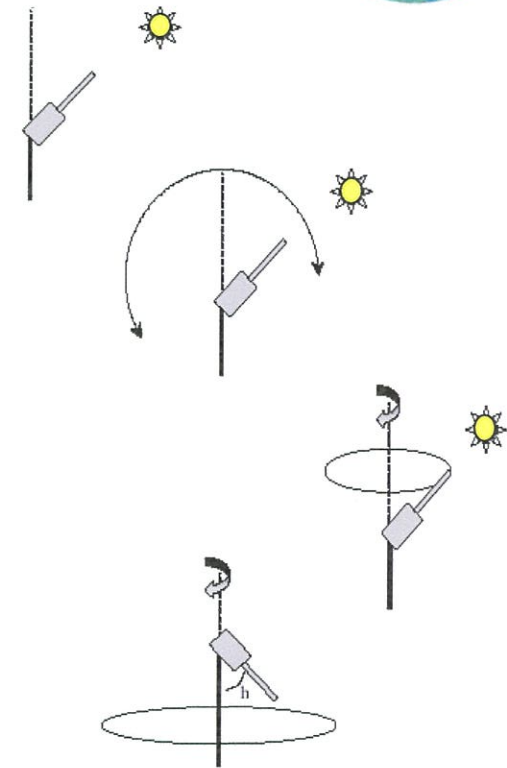
- Filters wheel : 8 filters + 1 dark plate
- 2 collimators and 2 detectors: Si and InGaAs

#	1	2	3	4	5	6	7	8	9	10	11	12	13
$\lambda(\text{nm})$	870Si	1600 InGaAs	670Si	1020 InGaAs	550Si		440Si		380Si	870InGaAs	1020Si		937Si

- Maintenance including calibration once a year



- ❑ « Sun » protocol
 - ❑ Direct sun view : extinction measurement
- ❑ « Principal plane » protocol
 - ❑ Sky radiance : measurements in the principal plane
- ❑ « Almucantar » protocol
 - ❑ Sky radiance : complete azimuth rotation for $\theta_v = \theta_s$
- ❑ « Ground » protocol (specific to this prototype)
 - ❑ Ground radiance measurements for different θ_v



- ⇒ Automatic and continuous acquisition :
first morning acquisition air mass < 5 - last evening acquisition air mass > 5
- ⇒ Complete measurement set every 90 min. : *SUN + ALM + PPL + GND (1st elevation) + SUN + GND (2nd elevation) + ... + GND (12th elevation) + SUN*
- ⇒ Transmitted to CNES every evening via a GSM link

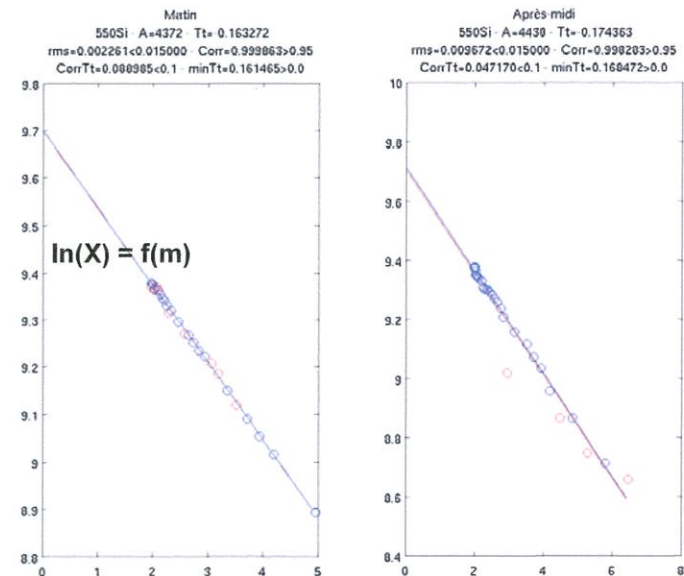


- Irradiance calibration
 - based on the Bouguer-Langley extinction law (all wavelength)

$$X_k = A_k * G_{uk} * I_k$$

(direct sun viewing)

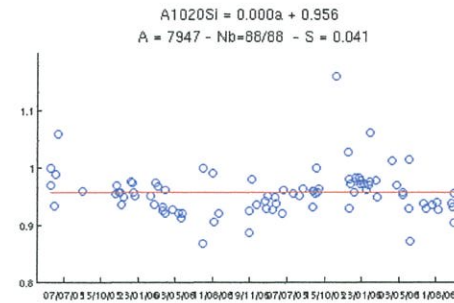
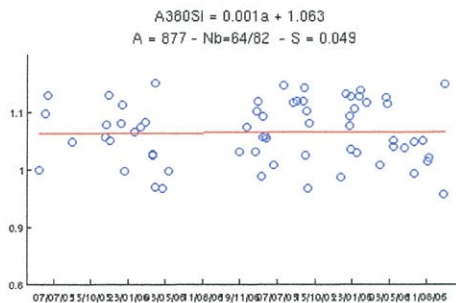
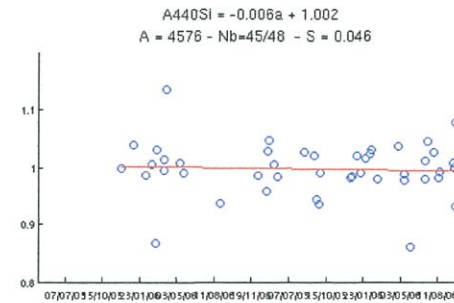
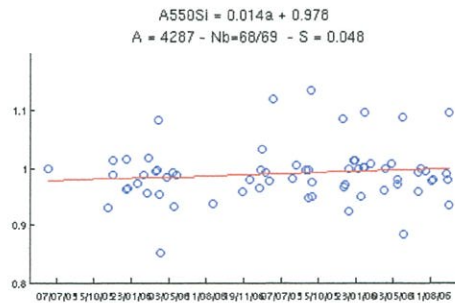
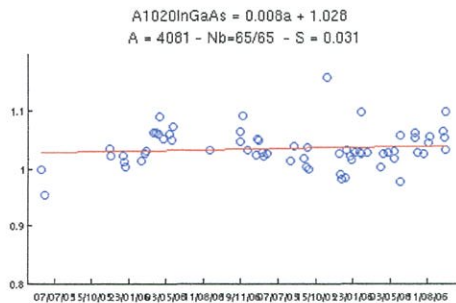
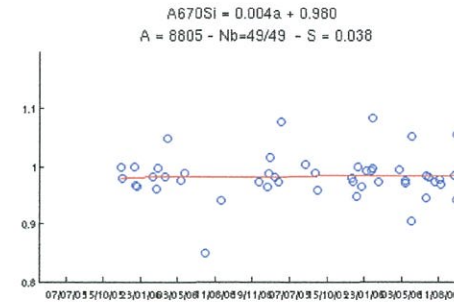
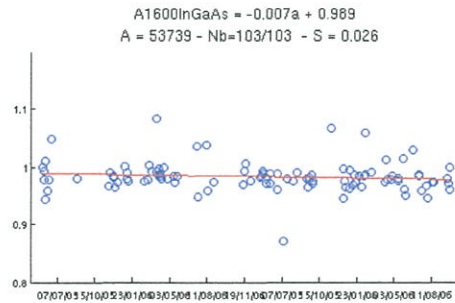
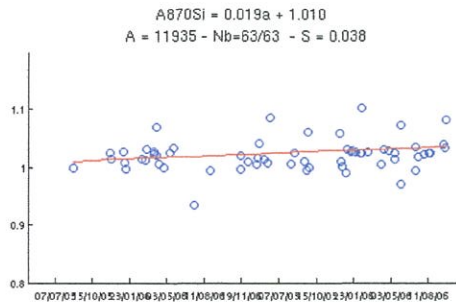
$$I_k = I_{0k} * (d/d_0) * \exp(-m * \tau_k)$$



A_k = instrument irradiance calibration coefficient



□ Irradiance calibration performed every day : A_k monitoring





□ Radiance calibration

- based on Rayleigh scattering for 380, 440, 550 nm bands

$$X_k = B_k * G_{kk} * L_k$$

(sky radiance in the principal plan)

L_k estimated using a radiative transfert code

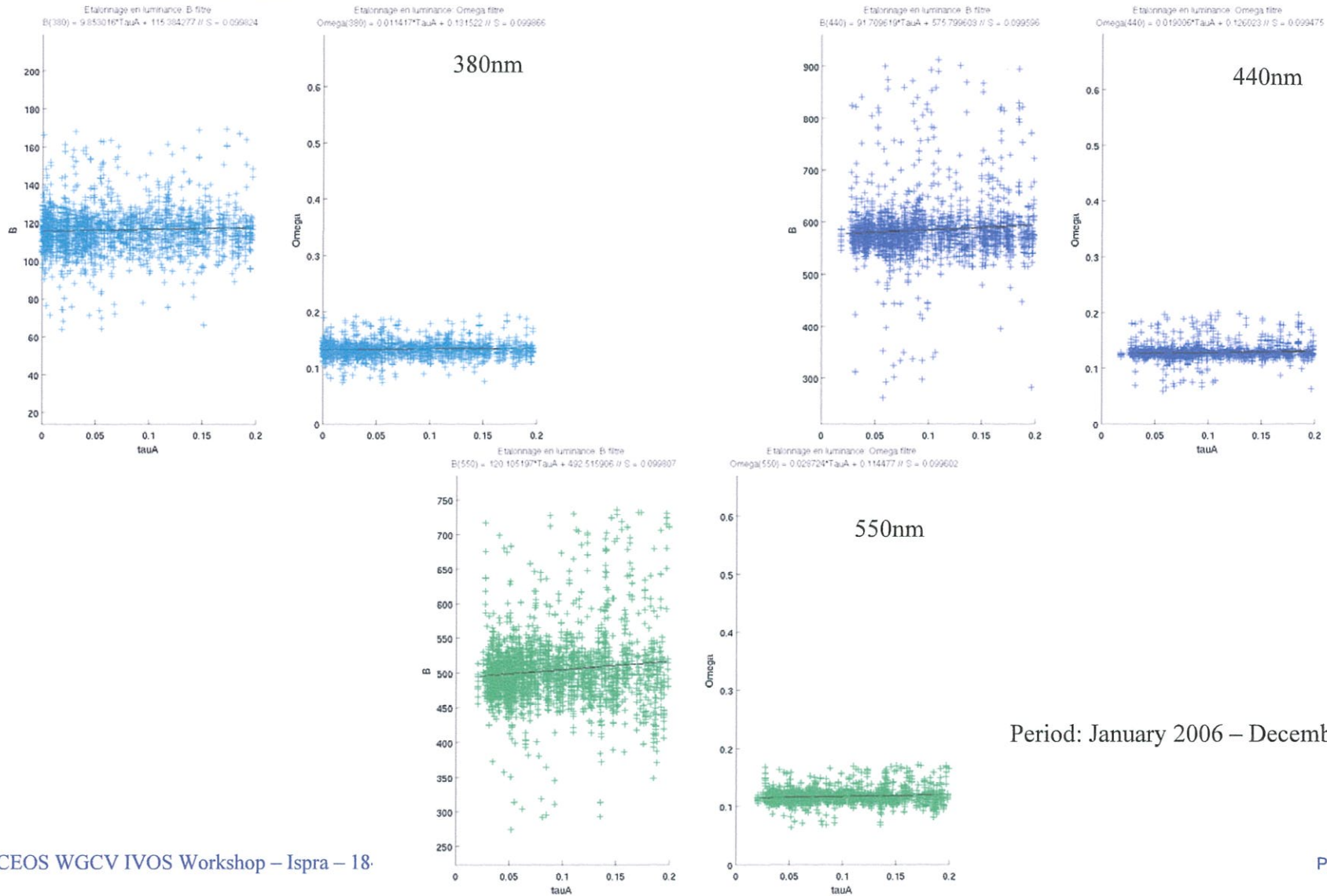
B_k = instrument radiance calibration coefficient

- $\Omega = B_k / A_k$: instrument solid angle (wavelength independent)

⇒ Computation of the radiance calibration coefficient for the other spectral bands (red, NIR and SWIR)



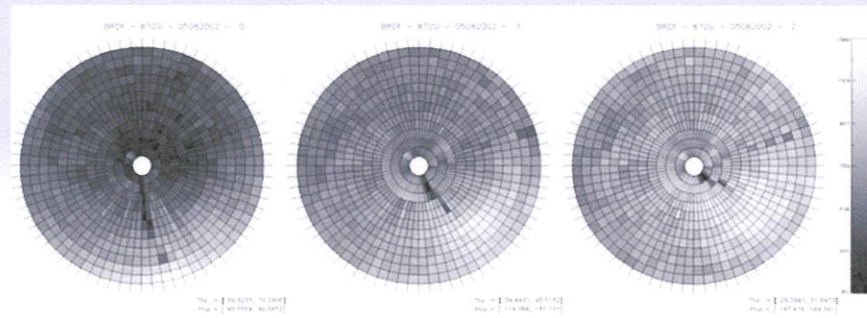
Rayleigh scattering calibration and Ω estimation



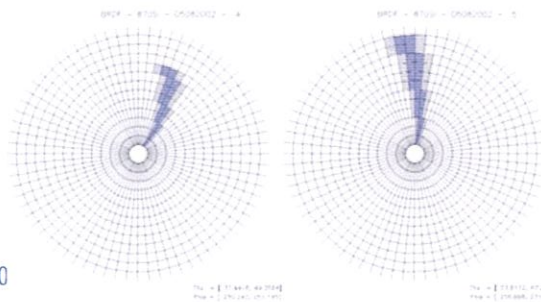
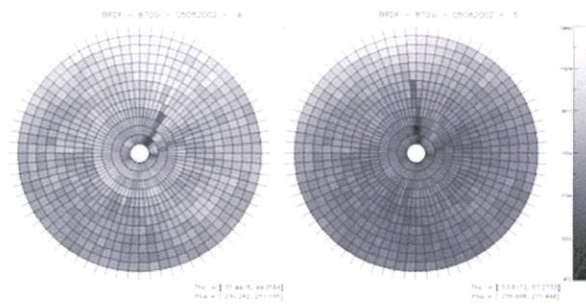
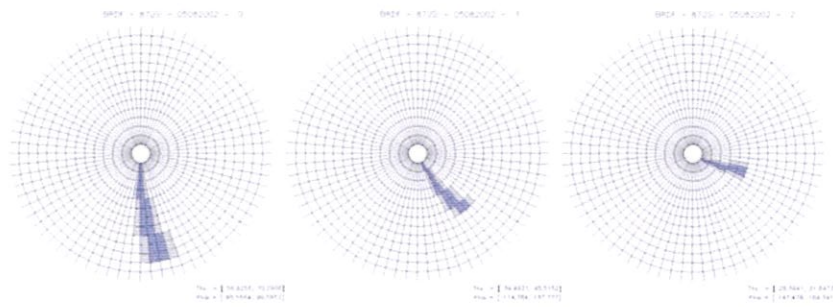
Period: January 2006 – December 2006



Ground reflectance

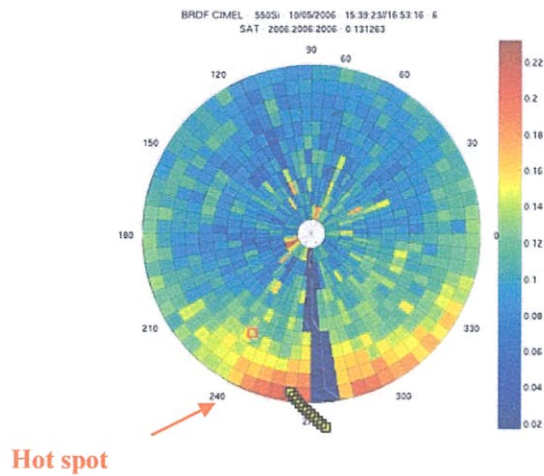


Shadow mask of the pole

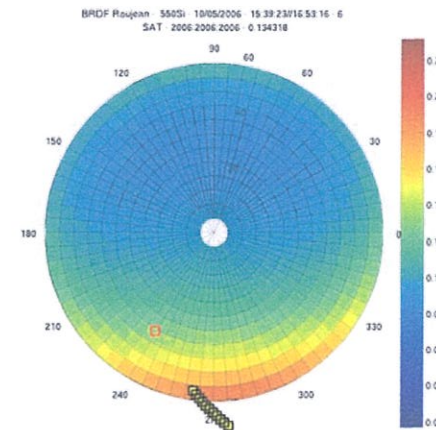




- Adjustment of a BRDF model (iterative filtering)

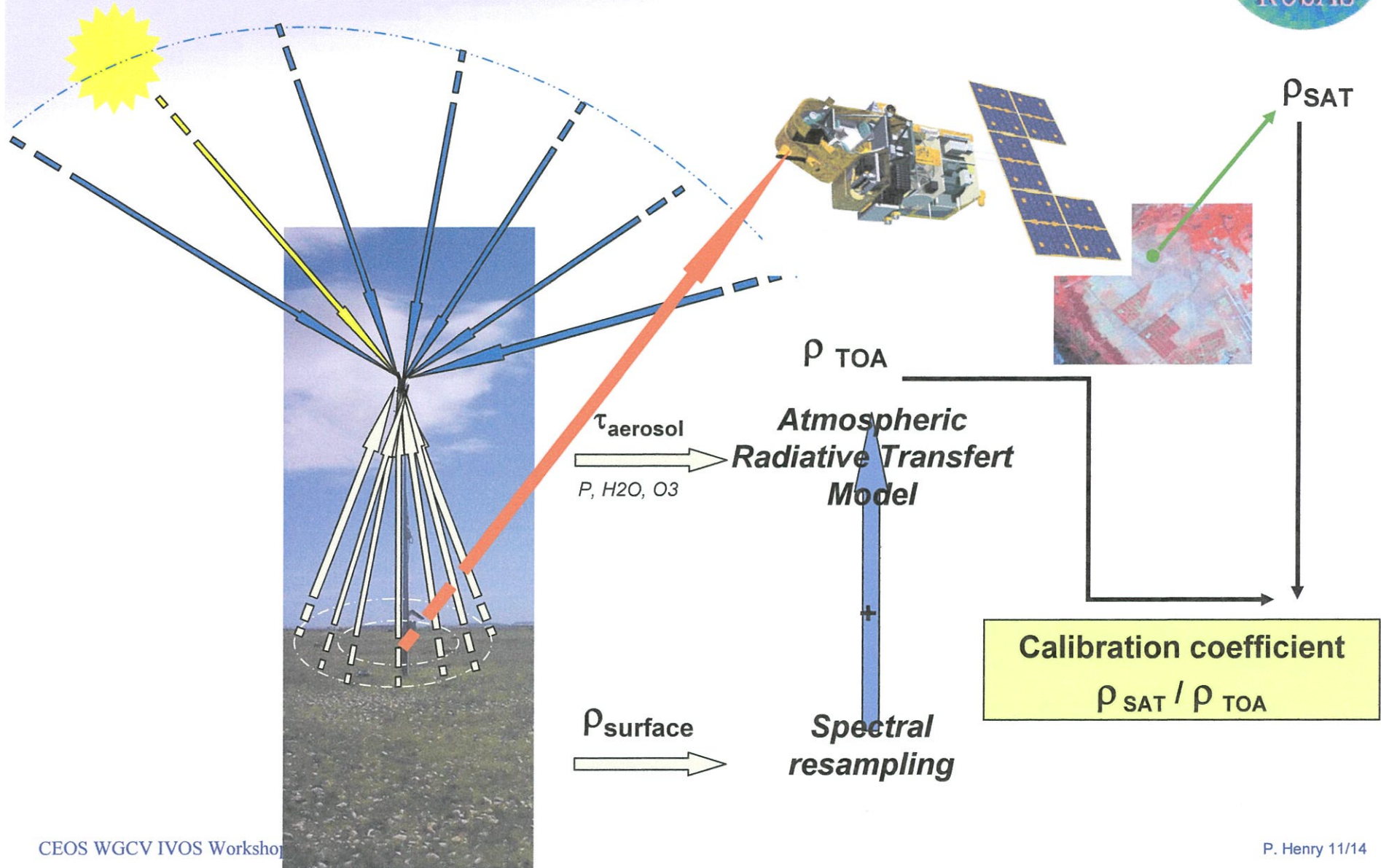


ROSAS ground reflectance (550nm)



Estimated BRDF model (550nm)

cnes In flight calibration procedure



SPOT4 calibration

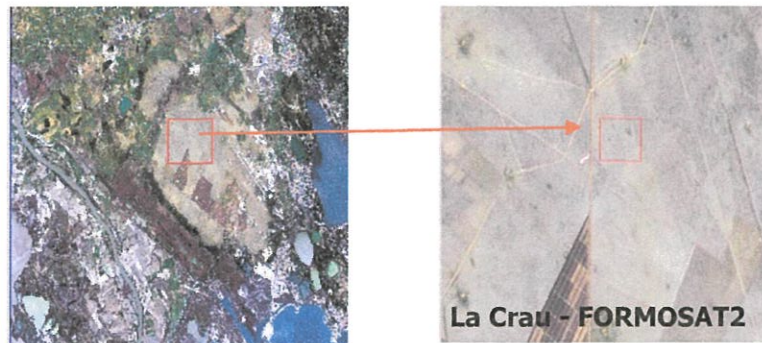


Date	B1 (green)	B2 (red)	B3 (NIR)
07-Nov-05	0.720	0.819	0.771
13-Mar-06	0.752	0.764	0.763
23-Mar-06	0.801	0.826	0.836
03-Apr-2006	0.770	0.824	0.786
02-Nov-06	0.732	0.822	0.794
13-Nov-06	0.751	0.842	0.796
22-Nov-06	0.729	0.807	0.789
Average	0.751	0.815	0.791
Standard deviation	0.026	0.023	0.022
Official cal. (01/06/06)	0.743	0.821	0.809
Discrepancy	+1.1%	-0.7%	-2.2%

- 😊 Low scattering over 7 measurements
- 😊 Good consistency with the official calibration
- 😞 No calibration for the SWIR band



- ❑ ROSAS : operational for SPOT calibration
 - ❑ one calibration campaign per year
- ❑ Successfully tested with a set of Formosat 2 images



- ❑ Development of an operational software for ROSAS data archiving, testing and processing
 - ❑ industrial development
 - ❑ friendly interfaces, calibration results traceability, expertise toolbox
 - ❑ acceptance : October 2010



- ❑ Improve the calibration method :
 - ❑ H₂O content using the 937nm band
 - ❑ extend the calibration to the SWIR domain
- ❑ Transfer the ROSAS software to the operational calibration team
- ❑ Calibrate Pleiades using ROSAS during in-flight commissioning
- ❑ Try to install a 2nd ROSAS system on a new calibration site
- ❑ Study a ROSAS evolution for the Sentinel-2 in-flight calibration